Session 10: SUGGAR++ Basics

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FUN3D Training Workshop July 27-28, 2010



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Learning Goals

- What this will teach you
 - Very rudimentary SUGGAR++ operation
- What you will not learn
 - All the useful stuff that Ralph Noack would teach you
 - GVIZ (Ralph's own viewer for overset grid assembly useful for debugging/assessing hole cutting)
- What should you already know
 - Basic concept of overset meshes





Setting

Background

- Use of overset grids in FUN3D requires either SUGGAR++ or SUGGAR (predecessor)
 - SUGGAR++ and SUGGAR are very similar in functionality and usage; will generally use "SUGGAR" and "SUGGAR++" interchangeably here; in one or two spots the differences are noted
 - Disclaimer: I am not a SUGGAR expert just a user for limited applications; this presentation may contain factual errors or other misinformation
- Compatibility
 - FUN3D requires both DiRTlib and SUGGAR codes from PSU
 - Grid formats: VGRID, AFLR3, FieldView (FV)
- Status
 - Overset simulations done with FUN3D and SUGGAR++ on a frequent basis, primarily for rotorcraft applications.





SUGGAR++ Documentation

- User's Guide: doc/UsersGuide/UsersGuide.pdf
 - Documents list of input elements (the rules, not much of the "why")
 - Documents command-line options for SUGGAR++
- Programmer's Guide: doc/ProgrammersGuide/ProgrammersGuide.pdf
 - Compilation
 - How to integrate libSUGGAR++ into a flow solver
- Training slides presented by Ralph Noack and Dave Boger at the April 2010 FUN3D Training Session will eventually make it on to the FUN3D website
 - Much of the material here is a distillation of the April slides but they had a full day to cover this





Nomenclature (1/4)

- SUGGAR: Structured, Unstructured, Generalized overset Grid AssembleR SUGGAR++ is the next-generation version
 - PEGASUS-like capability for general grids
 - Stand-alone versions for static grids; library versions for dynamic grids
- DiRTlib: Donor interpolation/Receptor Transaction library used by flow solver to handle data provided by SUGGAR++; no user input (just compile and link to flow solver)
- Component Grid
 - "Independently" generated grid for one piece of the configuration
 - Up to you to create these
- Composite Grid
 - An assembly of component grids
 - Created by SUGGAR++ based on your input





Nomenclature (2/4)

- Overset grid point classification
 - In or Active: flow solver updates these points by solving the governing equations at these locations
 - Out or Hole: flow solver need not update these points as they have been removed from the domain
 - In practice, especially for moving grids, the flow solver fills in data at these points by averaging neighboring points - done so that as points move from "out" to "in", they have "reasonable" data
 - Fringe: these points are updated by interpolation from "in" points; fringe points border a hole (inner fringe) or lie along an outer boundary (outer fringe)
 - Donor: the "in" points that supply data to fringe points
 - Orphan: fringe points for which too few or no donor points can be found; undesirable; solver fills in data at these points by averaging solution at neighboring points





Nomenclature (3/4)

• Flow solver point classification - example



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Nomenclature (4/4)

- DCI file
 - Domain Connectivity Information file
 - Created by SUGGAR; contains information about point classifications (hole, fringe, etc) for points in composite mesh, plus interpolation stencil data
 - Calls to DiRTlib within FUN3D read the DCI file and utilize the data within to update the solution at fringe points via interpolation from donor points
 - If grid is static, only need one DCI file
 - If grid is dynamic, must either have pre-computed DCI files available for the grid positions at each time step, or utilize libSUGGAR calls within FUN3D to compute DCI data "on the fly"





XML Basics (1/2)

- SUGGAR/SUGGAR++ input based on XML
 - eXtensible Markup Language (HTML-like, but not web-centric)
 - XML element is enclosed in a tag "< >", with corresponding end tag <body> ... </body> (start and end can also span multiple lines)
 - Elements can have attributes/data: <body name="wing">
 - Elements can have an implicit end tag; elements can be empty no attributes: <dynamic/>
 - XML elements can be embedded in other XML elements to create parent-child relationships (wing and store are children of aircraft)

```
<body name="aircraft">
```

```
<body name="wing">
```

```
</body>
```

```
<body name="store">
```

```
</body>
```

</body>





XML Basics (2/2)

- Element attributes are name/value pairs associated with an element
 - Always in the start tag, value must be in quotes (single or double) <body name=`blade_1'> ... </body> <translate axis=``x" value=``1.0e0"/>
- Comments start with <!-- and end with --> and cannot be within a tag

<!-- <body name="aircraft"/> --> Correct

<body <!-- name="aircraft" --> /> Incorrect

- XML syntax must be precise: xmllint is on most(?) systems and can be used to check XML syntax before using SUGGAR
 - Usage: xmllint myfile.xml
 - If syntax is OK, will simply echo XML file to screen; otherwise it reports the error
- Indentation helps keep XML input readable; xmllint can help here too
 - Usage: xmllint -format my_messy_file.xml > my_neat_file.xml

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Hole-Cutting: Hierarchy

- Parent-Child hierarchy established in XML file minimizes additional input to control hole cutting
- Basic rule: siblings cut each other
 - Geometry in one body (including all children) cut all grids in a sibling body (including all children); Aircraft cuts hole in Store and vice versa



Hole-Cutting: SUGGAR vs SUGGAR++

 Older SUGGAR code relies (primarily) on Octree hole cutting - uses Cartesian representation of geometry; hole cutting based on a query approach: Is this point inside (the Cartesian representation of) the body?



- In my experience, the Octree hole cutting approach often needs a lot of tweaking beyond the default behavior
- Newer SUGGAR++ code relies (primarily) on a direct hole cutting approach: Find intersections of geometry and grid; requires watertight geometry
- In my experience very little tweaking has been required with SUGGAR++
- SUGGAR++ supports the older Octree approach too; other hole-cutting options are available in both codes but are beyond the scope here
- There are pros and cons to any approach...



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Hole Cutting: Overlap Minimization

- Solution quality usually improved by reducing amount of overlap
- Goal is to have donors and receptors of similar size
- Enabled by element <minimize_overlap>
- For moving grids: <minimize_overlap keep_inner_fringe="yes"/>
 - Instead of blanking out points removed in overlap minimization, keeps them as fringes so they are *interpolated* rather than *averaged* presumably better for when these points later emerge from the hole





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Building Up A SUGGAR Input File (1/7)

- <global> element serves as the root (parent) element for every SUGGAR input file: first line in file is <global> and last line is </global>
- Child elements of <global> specify various global parameters, and the body hierarchy
- So on a high level an input file for an aircraft composed of a wing and a store would look something like:





Building Up A SUGGAR Input File (2/7)

- Common child elements of <global> (see documentation for more info)
 - <donor_quality value="0.9"/> (lower stencil quality standard to reduce number of orphans)
 - <minimize_overlap keep_inner_fringe="yes"/>
 - <output> (governs output of composite mesh and DCI file)
 - Principle children of <output>
 - <composite_grid filename="file" style="style"/>
 - <domain_connectivity filename="file" style="style"/>
 - Note: <composite_grid> and <donor_receptor_file> are for SUGGAR++; SUGGAR uses different element names, but accomplish the same thing





Building Up A SUGGAR Input File (3/7)

- <body> element can be child of <global> or another <body>
 - Required attribute is name="body_name"
- Common child elements of <body> (see documentation for more info)
 - <volume_grid name="wing" filename="Grids/wing"
 style="vgrid_set"/> (associates a volume grid with a body)
 - <dynamic> (declares a body as moving; also determines how the element <transform> is handled)
 - <transform> (used to manipulate body scale, rotate, translate, etc.)
 - If <transform> is child of <body>, transform is "static" input grid coordinates are actually altered by the transform specified
 - If <transform> is child of <dynamic>, transform is "dynamic" input grid coordinates are *not* altered by the transform; the transform is only used internally
 - I find this more than a little confusing...please see the documentation for yourself





Building Up A SUGGAR Input File (4/7)

- I deal with the <transform> duality by adopting the following fixed strategy for moving-body cases:
 - Always make it a child of <body> and not a child of <dynamic>
 - Add a "self-terminating" <dynamic/> child to any body I want to have in motion:

```
<body name="store">
  <dynamic/>
  <transform>
    <scale value= '1.66666666666667'/>
  </transform>
</body>
```

- Because the <dynamic/> element self terminates, <transform> is not a child of it
- I don't claim this is the "right" way...but it works for my applications
- Not an issue for non-moving bodies in the composite grid





Building Up A SUGGAR Input File (5/7)

- Children of <transform>:
 - <translate>
 - <rotate> (used to rotate about x, y, or z)
 - <rotate_about_v> (used to rotate about arbitrary vector axis)
 - <scale>

```
<body name="store">
  <dynamic/>
  <transform>
    <scale value= '1.66666666666667'/>
  </transform>
</body>
```

- The order of transforms is important; transforms applied in order specified in the input file
- Refer to documentation for complete rules about which elements are allowed as children, which are allowed as parent, allowable attributes, etc.





Building Up A SUGGAR Input File (6/7)

More complex example of <transform> from rotorcraft application

```
<body name="rotor1 blade2">
 <dynamic/>
    <transform>
      <translate axis="x" value=" 7.6520E-01"/>
      <translate axis="y" value=" 0.0000E+00"/>
      <translate axis="z" value=" 7.9600E-01"/>
      <rotate about v axis vector="0.0E+00, 1.0E+00, 0.0E+00" value="0.0E+00"
  originx="7.652E-01" originy="0.0E+00" originz ="7.96E-01"/>
      <rotate about v axis vector="1.0E+00, 0.0E+00, 0.0E+00" value="0.0E+00"
  originx="7.652E-01" originy="0.0E+00" originz ="7.96E-01"/>
      <rotate about v axis vector="0.0E+00, 0.0E+00, 1.0E+00" value="0.0E+00"
  originx="7.652E-01" originy="0.0E+00" originz ="7.96E-01"/>
      <rotate about v axis vector="0.0E+00, -1.0E+00, 0.0E+00" value="0.0E+00"
  originx="7.652E-01" originy="0.0E+00" originz ="7.96E-01"/>
      <rotate about v axis vector="0.0E+00, 0.0E+00, 1.0E+00" value="9.0E+01"
  originx="7.652E-01" originy="0.0E+00" originz ="7.96E-01"/>
    </transform>
  <volume grid name="rotor w cutout 1 correct pitch" style="vgrid set"</pre>
  filename="rotor w cutout 1 correct pitch" format="unformatted"
  precision="double">
 </volume grid>
```

</body>



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Building Up A SUGGAR Input File (7/7)

- Boundary conditions
 - SUGGAR needs to know some boundary condition information, e.g. which are the solid (body) boundaries, which outer boundaries need to be interpolated from other grids
 - SUGGAR input has provision for specifying the required SUGGAR BC's via XML elements
 - An alternative is to provide SUGGAR with a separate file with the BC data
 - I always use the separate file and so will not cover the xml input file approach - this is by far the most expedient way for VGRID meshes
- Pretty much wraps up this very brief overview of what goes into the input XML file for SUGGAR; documentation goes into much more and you should consult it in detail
- Next, look at how to set those BC's for SUGGAR via a file





Boundary Condition Files For SUGGAR

- SUGGAR++ needs BC info for each *component* grid set either via the SUGGAR++ input XML file OR an auxiliary file for each *component* grid; SUGGAR++ will output this auxiliary file for the *composite* mesh
- FUN3D also needs BC info for the *composite* grid; depending on grid type, file names / content may differ slightly between FUN3D / SUGGAR

	VGRID grid	FV grid	AFLR3 grid
FUN3D	grid.mapbc	grid.mapbc	grid.mapbc
	(standard VGRID file)	(not same as VGRID)	(<i>not</i> same as VGRID)
SUGGAR++	grid.mapbc	grid.ext.suggar_mapbc	grid.ext.suggar_mapbc
	(standard VGRID file)	(not same as VGRID)	(<i>not</i> same as VGRID)

- "ext" is the FUN3D grid extension, e.g.: grid.fvgrid_fmt, grid.r8.ugrid
- AFLR3 / FV grids: suggar_mapbc file has extra column; FUN3D ignores
- 3
 ! number of boundaries (patches)

 1 5000 Box
 farfield ! patch_index, fun3d_bc, family_name, suggar_bc

 2 4000 Wing_Surf
 solid

 3 -1
 Wing_FarFld overlap





Running SUGGAR/SUGGAR++ (1/3)

- Ralph recommends creating a "Grids" subdirectory and an "Input" subdirectory for each case
 - I never make an Input directory but do use a separate directory to hold the component grids
 - By default SUGGAR will look to read Input/Input.xml, so if you don't have this you simply have to explicitly give the input file name
- You will want to redirect stdout and stderr (stdout has LOTS of output); below, file name Input.xml_0 is explicitly given
 - c-shell
 - (./suggar++ Input.xml_0 > suggar++.output) > & suggar++.error
 - bourne-shell
 - ./suggar++ Input.xml_0 1> suggar++.output 2> suggar++.error
 - Simpler trick (just learned): ./suggar++ -reopen Input.xml_0
 - stdout and stderr automatically go to out.stdout++ and out.stderr++





Running SUGGAR/SUGGAR++ (2/3)

- Principle output: DCI and composite grid files specified in the XML file
- A concise summary of SUGGAR++ info is written to summary.log start time: Wed Jul 7 18:49:17 2010 host: i16n1 last git commit: command line: ./suggar++ Input.xml 0 number of processors: 1 number of threads: 1 total number of out: 9657 total number of fringes: 166124 total number of min fringes: 145265 total number of orphans: 199 number of orphans due to poor quality donors: 199 wall clock to perform assembly (seconds): 4.98748 memory used (MB): 1018.83 max interpolation deviation: 7.32747e-15 fringe donor quality: 0.904761 min fringe donor quality: 1



Running SUGGAR/SUGGAR++ (3/3)

- For FUN3D applications, SUGGAR++ itself is typically only run one time, to create the composite mesh and initial DCI file
- For moving-body cases, FUN3D calls libSUGGAR++ to compute the DCI data "on the fly"; however the libSUGGAR++ functionality is identical to SUGGAR++
- SUGGAR++ *can* be run in parallel
 - So far scaling achieved has been fairly poor nowhere near linear, even for small (~8) processor counts
 - Requires a separate partitioning step, which is at odds with current FUN3D parallel-processing paradigm; "optimum" SUGGAR++ partitioning bears no resemblance to optimal flow solver partitioning
 - For these reasons, and since libSUGGAR++ exhibits the same parallel issues, there has been minimal incentive to utilize the parallel capability for SUGGAR++ processing
 - Hopefully SUGGAR++ parallel scaling will improve in the future





Running SUGGAR/SUGGAR++ (3/3)

- Ralph has a "home-brew" interactive visualizer for looking at the overset grid assembly, called GVIZ
 - Allows visualization of the meshes, hole points, fringe points, etc.
 - Very useful for debugging
 - I don't have enough skill with GVIZ to even begin to explain how to use it





List of Key Input/Output Files

- Input
 - Input/Input.xml (default; any name OK if explicitly specified)
 - Component grids (name and grid format vary; for FUN3D: vgrid, aflr3, fieldview formats)
- Output
 - Composite grid; name and grid format vary
 - filename.dci (name set in XML file)
 - summary.log





FAQ's

- Where do I go to get the correct information on all this and not just your lame, watered-down interpretation?
 - SUGGAR/SUGGAR++ documentation
 - Ralph Noack
 - Sign up for the Google User Group: http://groups.google.com/ group/overset-grid-tools/topics (may require invitation from Ralph)





What We Learned

- Very basic SUGGAR/SUGGAR++ XML input
- Setting up a suggar_mapbc file
- SUGGAR/SUGGAR++ execution



